## Alternating Gradient Synchrotron Department Relativistic Heavy Ion Collider Project BROOKHAVEN NATIONAL LABORATORY Upton, New York 11973

Spin Note

AGS/RHIC/SN No. 017 (January 23, 1996)

# **Magnetic Field Error Coefficients for Helical Dipoles**

W. Fischer

January 16, 1996

For Internal Distribution Only

## Magnetic Field Error Coefficients for Helical Dipoles

Wolfram Fischer

January 16, 1996

#### 1 Introduction

The aim of this paper is to give a notation for the magnetic field error coefficients of helical dipoles. These coefficients shall be the magnetic multipole coefficients of ordinary dipoles when the helical wave length tends to infinity. Such a notation is different from Ref. [1].

For comparison, the magnetic field error notation for ordinary dipoles will be presented first. The notation for helical dipoles is given thereafter.

## 2 Magnetic Field Errors of Ordinary Dipoles

In a current free region in vacuum where the electrical field  $\vec{E}$  is constant, the magnetic field  $\vec{B}$  can be derived from a scalar potential  $\psi$  as

$$\vec{B} = -\nabla \psi. \tag{1}$$

We will use a Cartesian coordinate system (x, y, z) and a cylindrical coordinate system  $(r, \theta, z)$ . Here, x denotes the horizontal, y the vertical and z the longitudinal direction. Furthermore we have

$$\begin{aligned}
x &= r \cos \theta, \\
y &= r \sin \theta.
\end{aligned} \tag{2}$$

We consider a dipole of infinite length, thus neglecting fringe fields. The symmetry condition of such an element reads

$$\psi(r,\theta,z) = \psi(r,\theta,z+\Delta z) \tag{3}$$

where  $\Delta z$  is arbitrary. Therefore, the potential  $\psi$  is independent of z:

$$\psi(r,\theta,z) = \psi(r,\theta). \tag{4}$$

Having a main field  $B_0$  in y-direction, the solution of the Laplace equation  $\Delta \psi = 0$  can be written in cylindrical coordinates as

$$\psi(r,\theta) = -B_0 \left\{ r \sin \theta + \frac{1}{r_0^{n+1}} \frac{r^{n+1}}{r_0^n} \left[ a_n \cos \left( (n+1)\theta \right) + b_n \sin \left( (n+1)\theta \right) \right] \right\}.$$
 (5)

The term  $-B_0r\sin\theta$  gives the main field and the coefficients  $a_n$  and  $b_n$  denote deviations from the main field. The  $b_n$  are called "normal" and the  $a_n$  "skew" multipole coefficients. Here, the subscript "0" denotes a dipole, "1" a quadrupole etc.  $r_0$  is a reference radius. For the RHIC dipoles  $r_0 = \frac{5}{8}r_{coil}$  is used with  $r_{coil} = 40$  mm.

From equations (1) and (5) the magnetic field can be obtained in cylindrical coordinates. We have

$$B_r = B_0 \left\{ \sin \theta + \sum_{n=0}^{\infty} \left( \frac{r}{r_0} \right)^n \left[ a_n \cos \left( (n+1)\theta \right) + b_n \sin \left( (n+1)\theta \right) \right] \right\},$$

$$B_{\theta} = B_0 \left\{ \cos \theta + \sum_{n=0}^{\infty} \left( \frac{r}{r_0} \right)^n \left[ b_n \cos \left( (n+1)\theta \right) - a_n \sin \left( (n+1)\theta \right) \right] \right\}, \quad (6)$$

$$B_z = 0.$$

The Cartesian components of  $\vec{B}$  can be written as

$$B_{x} = B_{0} \left\{ \sum_{n=0}^{\infty} \left( \frac{r}{r_{0}} \right)^{n} \left[ a_{n} \cos(n\theta) + b_{n} \sin(n\theta) \right] \right\},$$

$$B_{y} = B_{0} \left\{ 1 + \sum_{n=0}^{\infty} \left( \frac{r}{r_{0}} \right)^{n} \left[ b_{n} \cos(n\theta) - a_{n} \sin(n\theta) \right] \right\},$$

$$B_{z} = 0,$$

$$(7)$$

which can also be expressed as

$$B_y + iB_x = B_0 \left[ 1 + \sum_{n=0}^{\infty} (b_n + ia_n) \left( \frac{x + iy}{r_0} \right)^n \right]. \tag{8}$$

Note that the European notation (see for example Ref. [2]) differs from the American one presented here. The transformation is

$$b_n(American) = b_{n+1}(European), \tag{9}$$

$$a_n(American) = -a_{n+1}(European).$$
 (10)

## 3 Magnetic Field Errors of Helical Dipoles

We consider again a magnet of infinite length, thus neglecting fringe fields. The symmetry condition for a helical dipole is

$$\psi(r,\theta,z) = \psi(r,\theta - k\Delta z, z + \Delta z),\tag{11}$$

where  $\Delta z$  is arbitrary. In other words,  $\theta - kz = const.$   $k = 2\pi/\lambda$  is the wave number and  $\lambda$  the wave length of the helix. k shall have the positive sign for right-handed and the negative sign for left-handed helices. Introducing the new variable

$$\tilde{\theta} = \theta - kz,\tag{12}$$

the symmetry condition (11) leads to a potential  $\psi$  which is only dependent on r and  $\tilde{\theta}$ :

$$\psi(r,\theta,z) = \psi(r,\tilde{\theta}). \tag{13}$$

The tilde shall remind the reader of the fact that  $\bar{\theta}$  in a helix is similar to  $\theta$  in a ordinary dipole. Using  $(r, \bar{\theta})$  as coordinates and having a transverse helical main Field  $B_0$  a solution of the Laplace equation  $\Delta \psi = 0$  is (cf. Eq. (5) and Ref. [1])

$$\psi(r,\tilde{\theta}) = -B_0 \left\{ \frac{4}{k} I_1(kr) \sin \tilde{\theta} + \frac{1}{n} \sum_{n=0}^{\infty} \frac{2^{n+1}(n+2)!}{(n+1)^{n+2}} \frac{1}{r_0^n k^{n+1}} I_{n+1}((n+1)kr) \times \left[ \tilde{a}_n \cos((n+1)\tilde{\theta}) + \tilde{b}_n \sin((n+1)\tilde{\theta}) \right] \right\}$$
(14)

where  $I_n$  are modified Bessel functions. Similar to the ordinary dipole case, the term  $-B_0\frac{4}{k}I_1(kr)\sin\tilde{\theta}$  yields the main field and the coefficients  $\tilde{b}_n$ ,  $\tilde{a}_n$  the deviations thereof. Here, the  $\tilde{b}_n$  are called "normal" and the  $\tilde{a}_n$  "skew" helical multipole coefficients (with respect to the direction of the main field  $B_0$ ). The subscript "0" denotes a helical dipole, the subscript "1" a helical quadrupole etc.  $r_0$  is again a reference radius.

The factors in (14) are chosen in such a way as to obtain the potential (5) when the helical wave length tends to infinity. In this case  $k \to 0$ ,  $\tilde{\theta} \to \theta$  and the Bessel function can be approximated by (cf. Ref. [3])

$$I_n(z) \approx \frac{1}{2^n} \frac{z^n}{(n+1)!}$$
 (15)

Now, the magnetic field can be computed as (cf. Ref. [1])

$$B_{r} = B_{0} \left\{ 4I'_{1}(kr) \sin \tilde{\theta} + \sum_{n=0}^{\infty} \frac{2^{n+1}(n+2)!}{(n+1)^{n+1}} \frac{1}{r_{0}^{n}k^{n}} I'_{n+1}((n+1)kr) \times \left[ \tilde{a}_{n} \cos((n+1)\tilde{\theta}) + \tilde{b}_{n} \sin((n+1)\tilde{\theta}) \right] \right\},$$

$$B_{\theta} = -\frac{1}{kr} B_{z},$$

$$B_{z} = -B_{0} \left\{ 4I_{1}(kr) \cos \tilde{\theta} + \sum_{n=0}^{\infty} \frac{2^{n+1}(n+2)!}{(n+1)^{n+1}} \frac{1}{r_{0}^{n}k^{n}} I_{n+1}((n+1)kr) \times \left[ \tilde{b}_{n} \cos((n+1)\tilde{\theta}) - \tilde{a}_{n} \sin((n+1)\tilde{\theta}) \right] \right\},$$
(16)

where  $I'_n$  denotes the derivative with respect to the argument of the Bessel function.

Since the Bessel function is nonlinear, the magnetic field of a helical dipole is nonlinear too, even the main field given by  $B_0$ . Close to the magnet axis we have  $r \to 0$  and the field can be approximated by

$$B_{x} = -B_{0} \sin(kz),$$

$$B_{y} = B_{0} \cos(kz),$$

$$B_{z} = -B_{0} k \left[ x \cos(kz) + y \sin(kz) \right],$$
(17)

i.e. even close to the magnet axis there is a longitudinal field component that will lead to coupling.

### References

- [1] V. Ptitsin, "Notes on the helical field", RHIC/AP/41 (1994).
- [2] J. Rossbach and P. Schmüser, "Basic course on accelerator optics", Fifth General Accelerator Course, University of Jyväskylä, Finland, CERN 94-01 (1994).
- [3] M. Abramowitz and I. Stegun, "Handbook of Mathematical Functions", Dover, New York (1972).